**Combining Probability-guided Contrastive Feature** Learning and Graph Neural Networks for Cytoarchitecture Classification in the Human Brain

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- **Postmortem** human brains
- Fixation in paraffine
- **Cut** into histological sections
- 6000-8000 sections per brain
- Thickness: 20µm



### Cytoarchitectonic Brain Areas







- Staining for **cell bodies**
- Light-microscopic imaging
- Resolution: 1µm/pixel
- up to 100'000 x 136'000 pixels
- up to 15 GB per image

**Goal:** Study the microstructural organization of the human brain to understand its functions.

• Microstructural reference for **brain atlases** [1, 2]

**Challenges:** limited annotations; complex and ambiguous structures; multi-scale patterns; artifacts

## Probability-guided Contrastive Feature Learning

**Idea:** Train a neural network to map image patches from

similar brain areas to similar feature vectors

### Cytoarchitecture Learning





• Extract **image patches** from microscopic images

# Graph Neural Networks for Cytoarchitecture Classification

**Idea:** Model cytoarchitecture classification as **graph node** 

classification task on approximate brain reconstructions

### Graph-based Framework

- Approximately reconstruct brain surface meshes
- Associate mesh nodes with **image locations**
- Compute deep cytoarchitectonic features
- Add additional features (location, probabilistic maps, annotations) to graph nodes
- Train graph neural networks (GNNs) to classify corresponding cytoarchitectonic areas for each node in the graph [5]



- Each image patch is associated with a discrete **probability vector** over cytoarchitectonic areas
- Probability vector indicates **how likely** a specific area occurs at a **specific location** in the brain
- Pairwise **similarity weight** is defined as crosscorrelation between probability vectors
- High correlation  $\rightarrow$  similar area  $\rightarrow$  similar features
- Low correlation  $\rightarrow$  different area  $\rightarrow$  **different features**
- **Contrastive learning:** Learn by comparing image patches in a training batch [3]
- Learned features enable cytoarchitecture classification

### Probabiliy-guided Contrastive Loss

feature vectors encoded  $z_i = f(X_i)$ by a neural network  $\left|\log \frac{\exp(\langle z_i, z_j \rangle / \tau)}{\sum_{k=1}^{N} \mathbb{I}_{i \neq k} \exp(\langle z_i, z_k \rangle / \tau)}\right|$ similarity weight between two  $\omega_{ij} = \langle p_i, p_j \rangle$ probability vectors number of image patches in a probability vector associated  $p_i \in \mathbb{R}^P$  . with an image patch training batch image patch extracted from a  $X_i$ **temperature** scaling parameter microscopic brain scan

motor area 4a **Probabilistic maps** from Julich-Brain [1] indicate the occurence probability of areas

at different locations

• GNNs combine local local **high-resolution image** features with neighborhood information







### Training & Evaluation

- Training with **categorical cross-entropy** using
- available expert annotations
- 1860 sections from 7 brains (80% train, 20% test)
- 325 sections from 8th brain (transferability check)
- JURECA-DC [4] (2 nodes, 8 NVidia A100 GPUs)
- Architecture: Graph Attention (GAT) [6] (3 layers)
- **Input:** cytoarchitecture features, probability
- vectors, canonical spatial coordinates [5]
- Performance measurement using macro-F1 score

# Conclusion & Future Work

- Probability-guided contrastive learning enables learning of useful cytoarchitectonic features without annotated training data • Graph Neural Networks efficiently integrate local features from high-resolution images with neighborhood information encoded in graphs • Future work • End-to-end learning of image and graph features • Cluster analysis as basis for data-driven
  - brain parcellation and knowledge discovery

#### Training & Neural Network Architecture



(transfer) brains. **sup:** supervised; **cont-sup:** contrastive supervised [5]; **cont-pmap:** contrastive pmap; **linear:** linear classification; **GNN:** GNN w. cytoarchitecture features; **GNN+**: GNN w. cytoarchitecture features, pmaps, and coordinates.

• Investigation of **limited transferability** to unseen brains

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